

INSTALLATION AND START-UP MANUAL

DIGITAL CONTROLLERS

**Honeywell**

DC 1010 – DC 1020 Series



Servizio Assistenza - Servicing Department  
e-mail [servicing@conflow.it](mailto:servicing@conflow.it)  
[www.conflow.it](http://www.conflow.it)



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## **CE CONFORMITY**

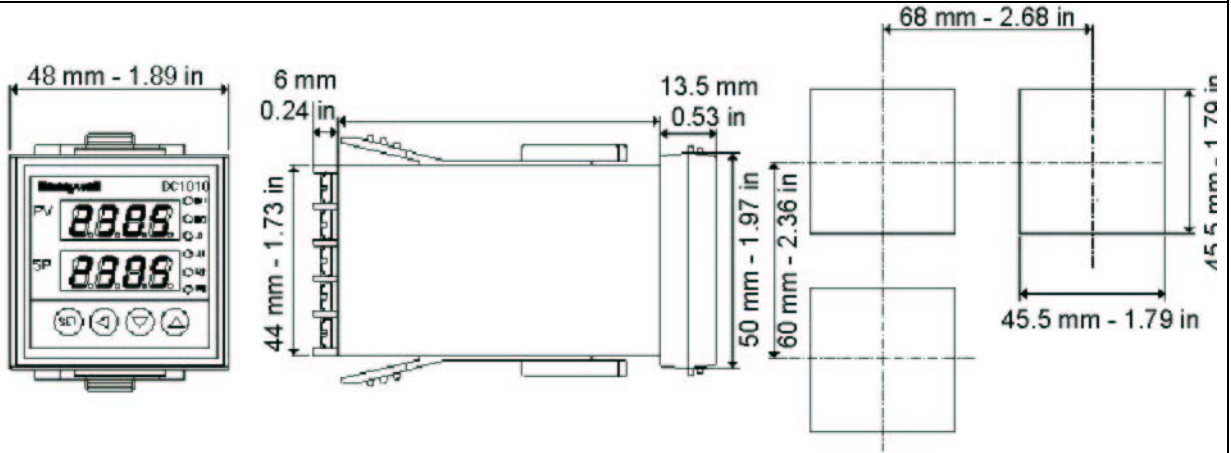
**This product is in conformity with the following European Council Directive:**

- **73/23/EEC**
- **89/336/EEC**

## 2. INSTALLATION INSTRUCTIONS

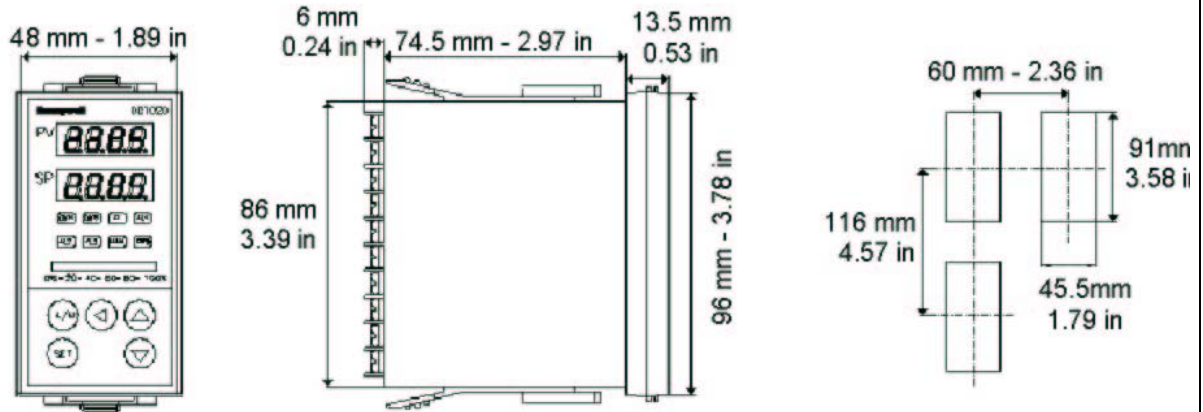
### DC 1010

#### DIMENSIONS AND PANEL CUT mm

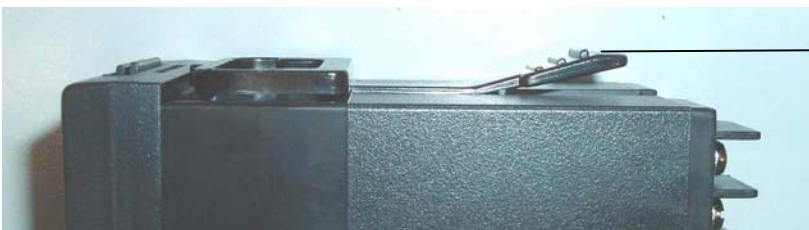


### DC 1020

#### DIMENSIONS AND PANEL CUT mm



## PANEL MOUNTING



MOUNTING BRACKET

To mount the controller into the panel follow the instruction :

1. Take off the mounting brackets
2. Put the controller on the panel
3. Bend the grip of the bracket and slide the bracket along the rail until the case is secured against the panel, put the grip of the bracket on the groove to fasten the case to the panel

## 3. WIRING DIAGRAMS



**WARNING** *The controller is considering "rack and panel mounted equipment" according EN61010-1. Conformity with 72/23/CE, requires the user to provide adequate protection against a shock hazard, the user must install the controller inside the panel that prevents OPERATOR access to the rear terminals*



**WARNING** *standard tension is equal to 85-264 V AC. Applying 85-264 VAC to a controller rated for 24 V DC will severely damage and is a fire and smoke hazard.*



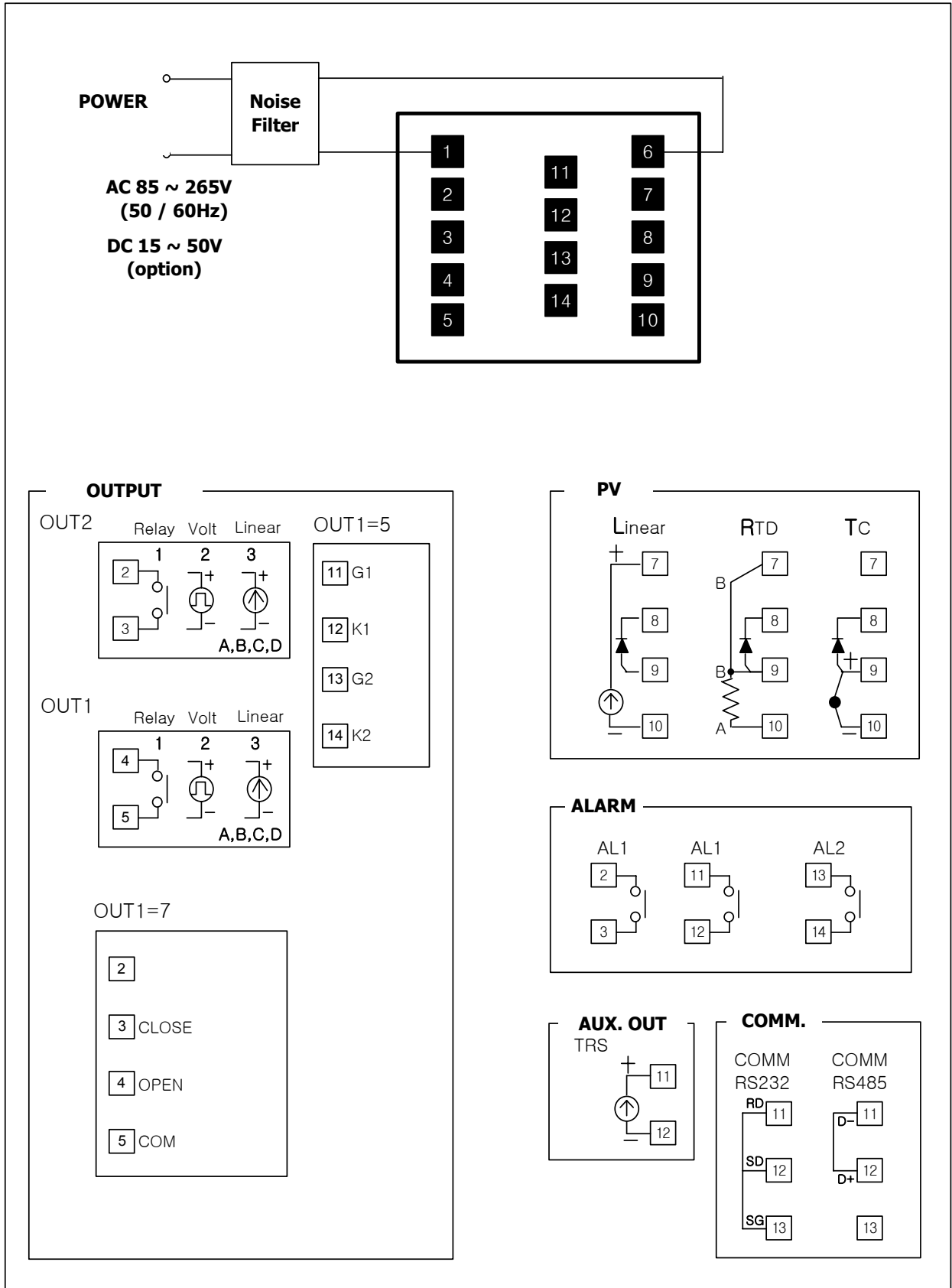
**WARNING WIRING REQUIREMENTS**  
*Shielded twisted pair cable are required for all Analog I/O, Process variables and computer interface circuits.*



**WARNING WIRING REQUIREMENTS**  
*Controllers do not have an internal electrical power switch. A switch or power main switch has therefore to be provided on the panel. This should be positioned close to the device and be easily accessible to the user and shall be labelled as the main isolator switch. The panel must also provide for power surge trips or fuses corresponding to standard IEC 364-4-41.*

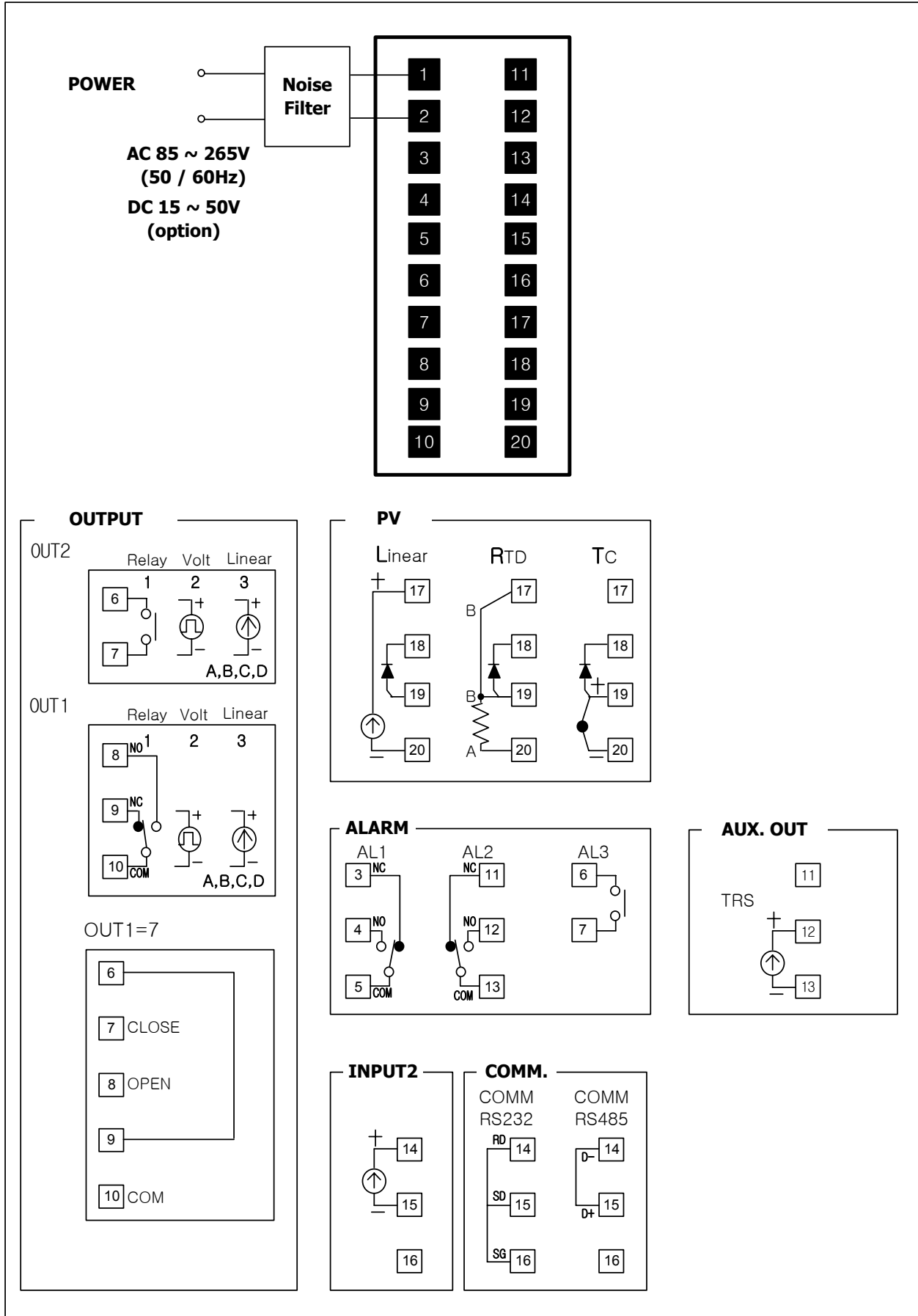
## WIRING DIAGRAM

### DC1010



## WIRING DIAGRAM

### DC1020



## 4. CONFIGURATIONS



### DISPLAY

**PV** – 4 digits dedicated to process variable ( red colour )

**SP** – 4 digits dedicated to set point ( green colour )

**BAR GRAPH** Horizontal – 10 green led bargraph indicates the value of the ouput in percentage

**LED OUT 1** – Status of output 1 green led on

**LED OUT 2** – Status of output 2 green led on

**LED AL 1** – Status of Alarm 1 red led on

**LED AL 2** – Status of Alarm 2 red led on

**MAN** – When the yellow led is on, the controller is in manual mode

**AT** – Autotuning operating with yellow led on

**PRO** – When a program is running the led flickers  
 When a program is suspended the led is on  
 When a program is running the led is off

### KEYS

**SET** – Allows moving from one parameter to another or saving new value of parameter or a status of parameter changed

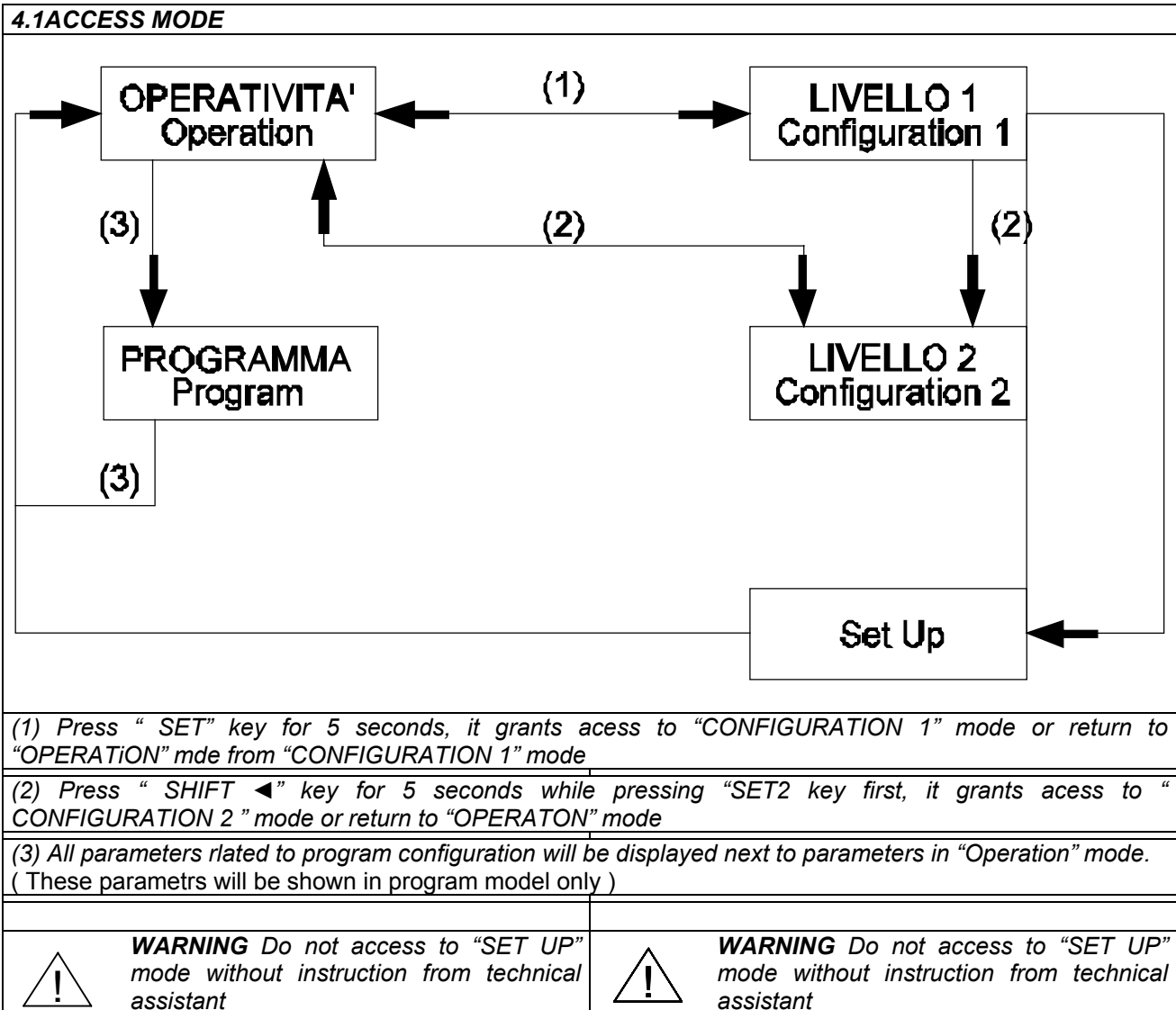
◀ - Allows shifting the digits to modify parameters

▲ - increase the value

▼ - decrease the value

**A/M** – AUTO-MANUAL mode





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## 1. Front Panel Overview

### 1.1 Display

PV : Process Value, 4-digit display (Color Red)

SP : Set Point, 4-digit display (Color Green)

### 1.2 LED Indicators

OUT1 : Output 1, color green

OUT2 : Output 2, color green

AT : Auto-Tuning, color yellow

PRO : Program, color yellow


AL1 : Alarm 1, color red


AL2 : Alarm 2, color red


MAN : Manual, color yellow

### 1.3 Keys

SET : MODE & SET key

 : SHIFT key

 : DOWN key

 : UP key

A/M : Auto/Manual key

## 2. Auto Tuning

2.1 When AT is set to 'YES', auto tuning can be initiated.

2.2 After completion of auto tuning, the PID parameter are automatically Entered into memory.

2.3 ATVL = auto tuning offset, the off set value when entered will be calculated and subtracted from the SP.

(It prevents over-shooting during auto tuning)

SP-ATVL = Auto-tuning value, ATVL = Auto tuning offset

Ex.) SP = 200°C, ATVL = 5, Auto tuning point is at 195°C

\* ATVL means auto-tuning point (195°C) in the above example.

2.4 Auto tuning failure

2.4.1 ATVL is too large.

→ If unsure, set ATVL = 0)

2.4.2 Process lag is to long for Auto Tune to function correctly.

→ Set PID parameter manually.

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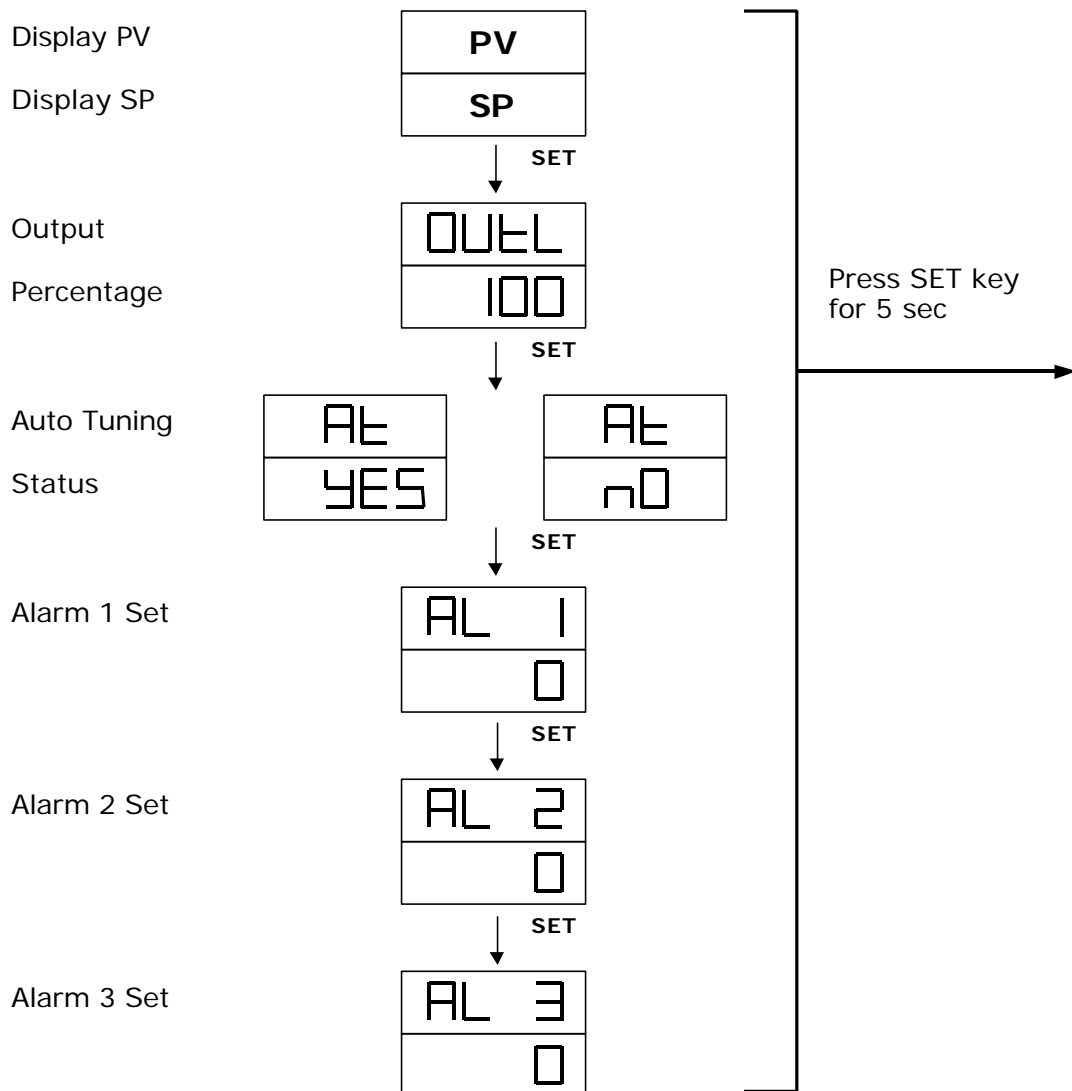
### 3. Error Information

1 n 1E	Open circuit sensor input 1
* A d C F	A/D converter failed
* C J C E	Cold junction compensation failed
1 n 2 E	Open circuit of sensor input 2
U U U 1	PV exceeds USPL
n n n 1	PV under LSPL
U U U 2	Input 2 signal has exceeded the upper limit
n n n 2	Input 2 signal has exceeded the lower limit
* r A C F	RAM failed
1 n E F	Interface failed
A U E F	Auto tuning failed

Note) Error \* code indicates critical failure unit must be replaced.

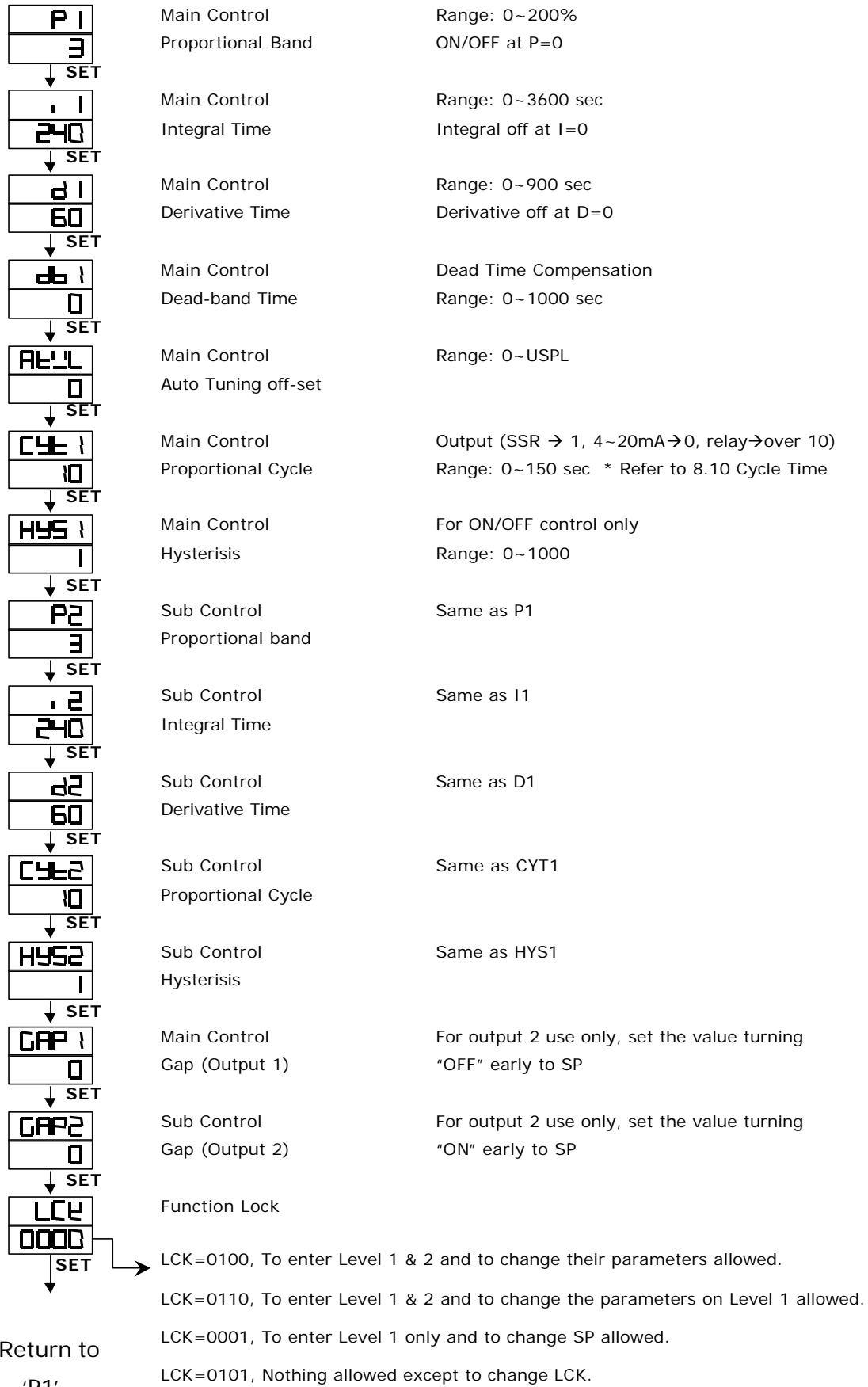
## 4. Operating Flow

### 4.1 Level 1



- 4.1.1 Press the SHIFT key ( $\triangleleft$ ) to change the parameters, when the SHIFT key is pressed, the first digit will start to blink. Press UP key ( $\triangle$ ) or DOWN key ( $\nabla$ ) to increase or decrease the value of the digit, then press SHIFT key again to go to the next digit, repeat the above procedure until the required has been selected. Press the SET key to enter the desired value.
- 4.1.2 The SET key also has the function of changing MODEs. If SET key is pressed, the display shows the next MODE.
- 4.1.3 Press SET key for 5 sec. The display goes to level 2, press the SET key again to return to level 1.
- 4.1.4 If any key is not pressed for 1 minute the display will return to level 1.
- 4.1.5 If the A/M key is pressed the controller will switch to level 1.
- 4.1.6 If the output percentage is "0", the controller output is off.

4.2 Level 2



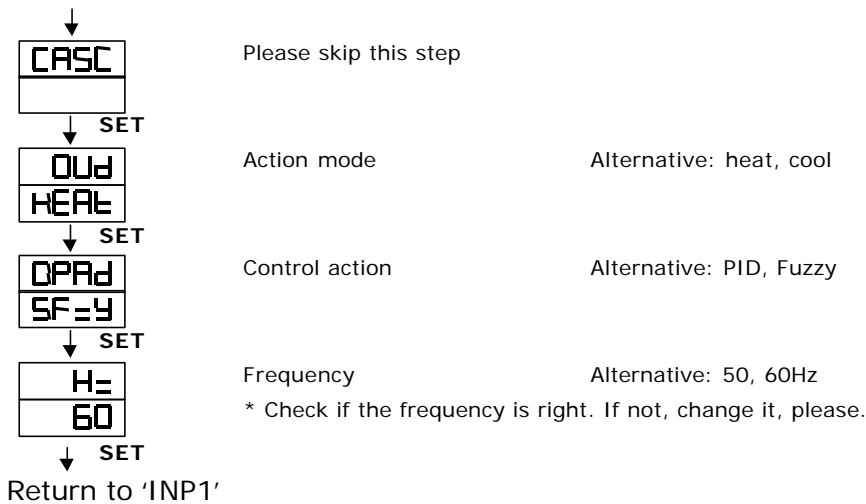
Return to  
'P1'

### 4.3 Level 3

When LCK=0000, press the SET key and SHIFT key for 5 seconds to enter level 3.

<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">INP1</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">E2</div> <p style="text-align: center;">↓ SET</p>	<p>Main Control Input Selection</p>	<p>Select the input range. Refer to 5.1 Input selection on P.13~P.14</p>
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">ANL1</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">0</div> <p style="text-align: center;">↓ SET</p>	<p>Main Control Analog Zero set</p>	<p>Used as input code which are AN1 to AN5 Range: LSPL~USPL</p>
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">ANH1</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">5000</div> <p style="text-align: center;">↓ SET</p>	<p>Main Control Analog Span set</p>	<p>Same as ANL1</p>
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">dP</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">0000</div> <p style="text-align: center;">↓ SET</p>	<p>Decimal point</p>	<p>To set the position of decimal point</p>
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">LSPL</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">00</div> <p style="text-align: center;">↓ SET</p>	<p>Lower Set-point limit</p>	<p>To set the lowest point within INP1</p>
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">USPL</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">4000</div> <p style="text-align: center;">↓ SET</p>	<p>Upper Set-point limit</p>	<p>To set the highest point within INP1</p>
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">ANL2</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">0</div> <p style="text-align: center;">↓ SET</p>	<p>Sub Control Analog Zero set</p>	<p>Used as input code which are AN1 to AN5 Range: LSPL~USPL</p>
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">ANH2</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">5000</div> <p style="text-align: center;">↓ SET</p>	<p>Sub Control Analog Span set</p>	<p>Same as ANL2</p>
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">ALd1</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">01</div> <p style="text-align: center;">↓ SET</p>	<p>Alarm mode of AL1</p>	<p>Range: 00~19 Refer to '6.1 Alarm Function Selection' on P.15</p>
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">ALt1</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">0</div> <p style="text-align: center;">↓ SET</p>	<p>Time set of Alarm 1</p>	<p>Used in program function (Range: 0~99.59 min.) 0=switching, 99.59=continuous, others = on delay time</p>
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">ALd2</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">01</div> <p style="text-align: center;">↓ SET</p>	<p>Alarm mode of AL2</p>	<p>Range: 00~19</p>
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">ALt2</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">0</div> <p style="text-align: center;">↓ SET</p>	<p>Time set of Alarm 2</p>	<p>Same as ALT 1</p>
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">ALd3</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">01</div> <p style="text-align: center;">↓ SET</p>	<p>Alarm mode of AL3</p>	<p>Range: 00~19</p>
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">ALt3</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">0</div> <p style="text-align: center;">↓ SET</p>	<p>Time set of Alarm 3</p>	<p>Same as ALT 1</p>
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">HYSA</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: 0 auto;">0</div> <p style="text-align: center;">↓ SET</p>	<p>Hysterisis of Alarm</p>	<p>Range: 0~1000</p>

↓ CLO1 150 ↓ SET	Main Control Calibration	To calibrate the low value of output Range: LSPL~USPL (Current output only)
CH01 3500 ↓ SET	Main Control Calibration high	To calibrate the high value of output Range: 0~9999 (Current output only)
CLO2 150 ↓ SET	Sub control Calibration low	Same as CL01
CH02 3500 ↓ SET	Sub Control Calibration high	Same as CH01
CLO3 150 ↓ SET	Transmitter control Calibration low	Same as CL01
CH03 3500 ↓ SET	Transmitter control Calibration high	Same as CH01
PUCY 00 ↓ SET	Timer for Motor valve control	Full run time of proportional motor (without potentiometer) Range: 5~200 sec
WAIT 0 ↓ SET	To use in program for waiting continued operation	0=No wait Others = Wait time
SETA 0000 ↓ SET	Relay Contact & Program RUN & End ALM	0= "a" contact, 1= "b" contact SET A.4=0 RUN alarm, SET A.4=1 END alarm
IDNO 1 ↓ SET	ID number (please skip this step)	Communication ID number
BAUD 2400 ↓ SET	Baud rate (please skip this step)	UART band rate selection Range: 110~9600 BIT/sec
SPDS 0 ↓ SET	Compensate SP	Range: -1000~1000
PVDS 0 ↓ SET	Compensate PV	Range: LSPL~USPL
Unit C ↓ SET	Unit of PV & SP	Range: C, F, A (analog)
SOFT 1000 ↓ SET	Soft filter (please skip this step)	Adjust the response time of PV (the bigger, the faster) Range: 0.05~1.00



#### 4.4 Level 4 (LOCK FUNCTION)

##### 4.4.1 Functions of LCK

LCK=0100, To enter Level 1 & 2 and to change their parameters allowed.

LCK=0110, To enter Level 1 & 2 and to change the parameters on Level 1 allowed.

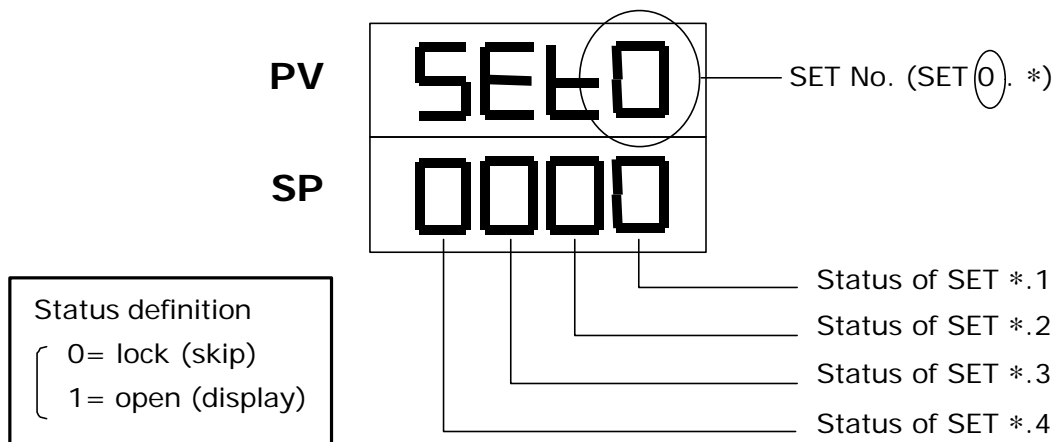
LCK=0001, To enter Level 1 only and to change SP allowed.

LCK=0000, To enter Level 3 allowed then press SET + SHIFT key (◀)

LCK=1111, To enter Level 4 allowed then press SET + SHIFT key (◀)

LCK=0101, Nothing allowed except to change LCK.

4.4.2 Let the display go to "LCK" in level 2, and set "1111" in LCK, then press SET key and SHIFT key (◀) for 5 seconds to enter "SET" status. There are SET0.1 to SET9.4 for use.





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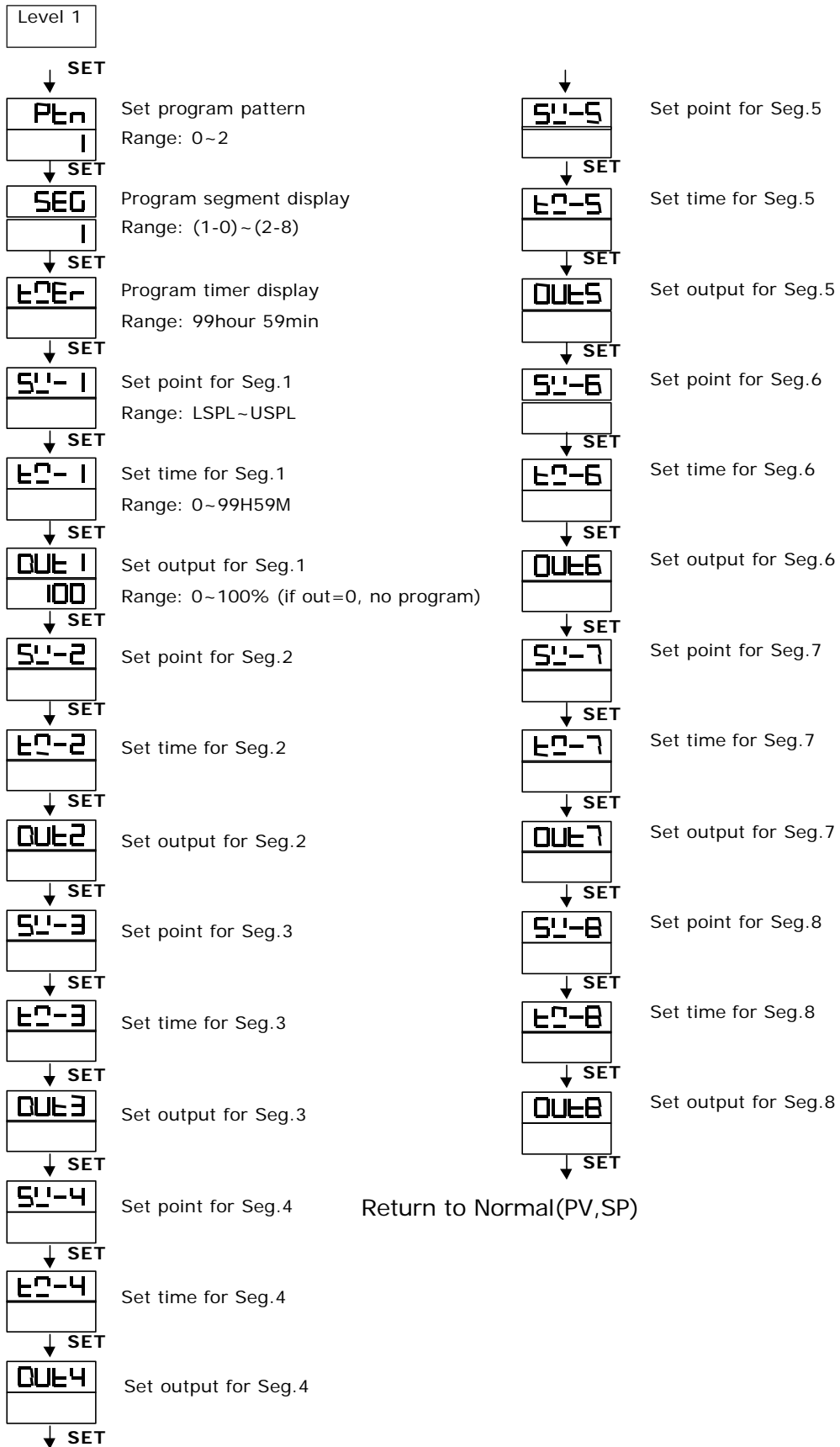
#### 4.4.3 Functions of SETs

<b>SET</b>	<b>Function</b>	<b>SET</b>	<b>Function</b>
1.1	OUTL	5.1	CL02, CH02
1.2	AT	5.2	CL03, CH03
1.3	AL1	5.3	Rucy, WAIT, HYSM
1.4	AL2	5.4	IDNO, BAUD
2.1	AL3	6.1	SVOS
2.2	ANL1, ANH1, DP	6.2	PVOS
2.3	LSPL, USPL	6.3	UNIT
2.4	ANL2, ANH2	6.4	SOFT
3.1	ALD1	7.1	CASC
3.2	ALT1	7.2	ODD
3.3	ALD2	7.3	OPAD
3.4	ALT2	7.4	Hz
4.1	ALD3		
4.2	ALT3		
4.3	HYSA		
4.4	CL01, CH01		

<b>SET</b>	<b>Function</b>	<b>Remarks</b>
8.1	0= No Repeat	Program Use
	1= Program Repeat	
8.2	0= No Power Failure	
	1= With Power Failure	
8.3	0= Start from 0	
	1= Start from PV	
9.3	TRS SP	Auxiliary Output Use
9.4	TRS PV	
0.3	0= No Remote SP	
	1= Remote SP	

\* Caution: Please don't operate SET8.4, otherwise the process of the controller will be in confusion.

## 4.5 Program Level



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4.5.1 This program has 2 patterns, each pattern contains 8 segments. The segment can be arranged a period of RAMP status or SOAK status.

4.5.2 Terminologies

Pattern : A program consists of some segments

Step : A RAMP status + a SOAK status

RAMP status : The status with changing SP

SOAK status : The status with fixed SP

4.5.3 Operating

1) Key functions (No changing parameters)

△ (START) : To start program procedure, PRO in panel flicker

▽ (WAIT) : To suspend program procedure, PRO in panel will stop flicker but light

△+SET (JUMP) : To jump segment

▽+SET (RESET) : To reset program procedure, PRO in panel will be "off"

2) Alarm function

If ALD1 to be set 07 (\*refer to the selection),

AL1 to be set 2 (AL1=2, it means alarm in segment 2 end),

ALT1 to be set 00.10 (alarm time 10 sec.).

\*In this case, when program proceeds to segment 2 end, ALM1 relay will be on 10 sec.

3) End function

If ALD to be set 17 (\* refer to the selection), this program will be end in segment 8 or 16.

\* In this case, PV and END will flicker in display window, and the alarm relay acts.

This controller does not have END order if program procedure are less than 8 segments. In this case, please set next segment's out=0, then this program will be end in last set segment. Otherwise, it will proceed 8 or 16 segments.

4) Linking function

PTN=1, Proceed pattern1, which contains 8 segments

PTN=2, Proceed pattern2, which contains 8 segments

PTN=0, linking proceed pattern 1 and 2 ,totally 16 segments

(Set PTN1 and PTN2 first, then set PTN=0)

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5) Other function (\*refer to level 4)

SET8.1=1 Program repeat

SET8.2=0 No power failure

SET8.2=1 With power failure function

(If power suspended, the controller will keep the memory)

SET8.3=0 Program start from 0

SET8.3=1 Program start from PV

## 5. Input

### 5.1 Input selection (INP 1)

TYPE	CODE	RANGE	HEX
K	K1	0.0~200.0°C/0.0~392.0°F	01H
	K2	0.0~400.0°C/0.0~752.0°F	02H
	K3	0.0~600.0°C/0.0~1112.0°F	03H
	K4	0.0~800.0°C/0.0~1472.0°F	04H
	K5	0.0~1000.0°C/0.0~1832.0°F	05H
	K6	0.0~1200.0°C/0.0~2192.0°F	06H
J	J1	0.0~200.0°C/0.0~392.0°F	07H
	J2	0.0~400.0°C/0.0~752.0°F	08H
	J3	0.0~600.0°C/0.0~1112.0°F	09H
	J4	0.0~800.0°C/0.0~1472.0°F	0AH
	J5	0.0~1000.0°C/0.0~1832.0°F	0BH
	J6	0.0~1200.0°C/0.0~2192.0°F	0CH
R	R1	0.0~1600.0°C/0.0~2912.0°F	0DH
	R2	0.0~1769.0°C/0.0~3216.0°F	0EH
S	S1	0.0~1600.0°C/0.0~2912.0°F	0FH
	S2	0.0~1769.0°C/0.0~3216.0°F	10H
B	B1	0.0~1820.0°C/0.0~3308.0°F	11H
E	E1	0.0~800.0°C/0.0~1472.0°F	12H
	E2	0.0~1000.0°C/0.0~1832.0°F	13H
N	N1	0.0~1200.0°C/0.0~2192.0°F	14H
	N2	0.0~1300.0°C/0.0~2372.0°F	15H
T	T1	-199.9~400.0°C/-199.9~752.0°F	16H
	T2	-199.9~200.0°C/-199.9~392.0°F	17H
	T3	0.0~350.0°C/0.0~662.0°F	18H
W	W1	0.0~2000.0°C/0.0~3632.0°F	19H
	W2	0.0~2320.0°C/0.0~4192.0°F	1AH
PLII	PL1	0.0~1300.0°C/0.0~2372.0°F	1BH
	PL2	0.0~1390.0°C/0.0~2534.0°F	1CH
U	U1	-199.9~600.0°C/-199.9~999.9°F	1DH
	U2	-199.9~200.0°C/-199.9~392.0°F	1EH
	U3	0.0~400.0°C/0.0~752.0°F	1FH
L	L1	0.0~400.0°C/0.0~752.0°F	20H
	L2	0.0~800.0°C/0.0~1472.0°F	21H

\* The initial set in factory mode is K2 without any certain requirement.

TYPE	CODE	RANGE	HEX
JIS Pt100	JP1	-199.9~600.0°C/-199.9~999.9°F	22H
	JP2	-199.9~400.0°C/-199.9~752.0°F	23H
	JP3	-199.9~200.0°C/-199.9~392.0°F	24H
	JP4	0.0~200.0°C/0.0~392.0°F	25H
	JP5	0.0~400.0°C/0.0~752.0°F	26H
	JP6	0.0~600.0°C/0.0~1112.0°F	27H
DIN Pt100	DP1	-199.9~600.0°C/-199.9~999.9°F	28H
	DP2	-199.9~400.0°C/-199.9~752.0°F	29H
	DP3	-199.9~200.0°C/-199.9~392.0°F	2AH
	DP4	0.0~200.0°C/0.0~392.0°F	2BH
	DP5	0.0~400.0°C/0.0~752.0°F	2CH
	DP6	0.0~600.0°C/0.0~1112.0°F	2DH
JIS Pt50	JP.1	-199.9~600.0°C/-199.9~999.9°F	2EH
	JP.2	-199.9~400.0°C/-199.9~752.0°F	2FH
	JP.3	-199.9~200.0°C/-199.9~392.0°F	30H
	JP.4	0.0~200.0°C/0.0~392.0°F	31H
	JP.5	0.0~400.0°C/0.0~752.0°F	32H
	JP.6	0.0~600.0°C/0.0~1112.0°F	33H
AN1	AN1	-10~10mV/-1999~9999	34H
AN2	AN2	0~10mV/-1999~9999	35H
AN3	AN3	0~20mV/-1999~9999	36H
AN4	AN4	0~50mV/-1999~9999	37H
AN5	AN5	10~50mV/-1999~9999	38H

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## 6. Alarm

### 6.1 Alarm function selection

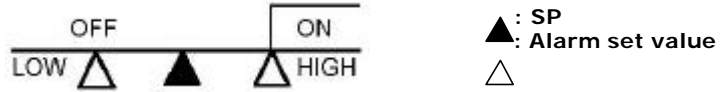
CODE	DESCRIPTION	Hold-On
00/ 10	None	
01	Deviation high limit alarm	Yes
11	Deviation high limit alarm	No
02	Deviation low limit alarm	Yes
12	Deviation low limit alarm	No
03	Deviation high/low alarm	Yes
13	Deviation high/low alarm	No
04/ 14	Deviation high/low range alarm	No
05	Absolute value high limit alarm	Yes
15	Absolute value high limit alarm	No
06	Absolute value low limit alarm	No
16	Absolute value low limit alarm	Yes
07	Segment end alarm (use for program only)	-
17	Program run alarm (use for program only)	-
08	System error alarm-on	-
18	System error alarm-off	-
19	On delay timer alarm	-

\* Note : "Hold-On" means the alarm does not work at the first time.

6.2 Alarm action description

6.1.1 CODE 00/10 : None

6.1.2 CODE 01 : Deviation high alarm inhibit



6.2.3 CODE 11 : Deviation high alarm no inhibit



6.2.4 CODE02 : Deviation low alarm inhibit



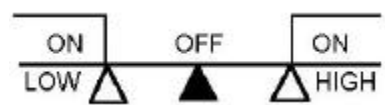
6.2.5 CODE12 : Deviation low alarm no inhibit



6.2.6 CODE03 : High/low alarm inhibit



6.2.7 CODE13 : High/low alarm no inhibit



6.2.8 CODE04/14 : Band alarm



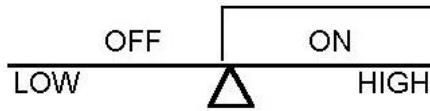
6.2.9 CODE05 : Absolute high alarm inhibit



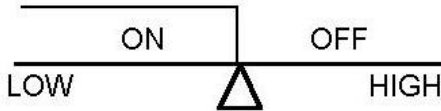


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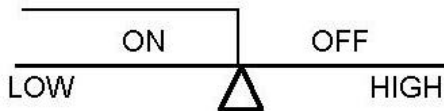
6.2.10 CODE15 : Absolute high alarm no inhibit



6.2.11 CODE06 : Absolute low alarm inhibit



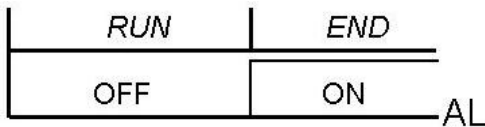
6.2.12 CODE16 : Absolute low alarm no inhibit



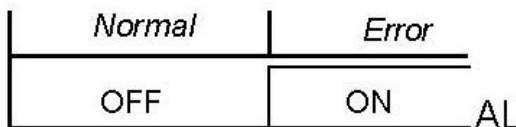
6.2.13 CODE07 : Segment end alarm (program only)

- i) ALD 1~3, set 07
- ii) AL1~3, alarm segment no. set
- iii) ALT1~3, if set 0 = flicker alarm  
set 99.59 = alarm continued  
set others = on delay time

6.2.14 CODE17 : Program run alarm (program only)



6.2.15 CODE08 : System Error- ON



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6.2.16 CODE18 : System Error-OFF

<i>Normal</i>	<i>Error</i>
ON	OFF

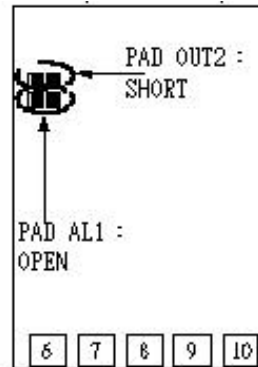
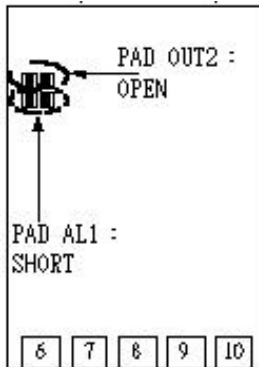
AL

6.2.17 CODE19 : on delay timer  
when PV=alarm SP, it keeps a certain period (set time)  
before alarm action (Range: 00H00M~99H59M)

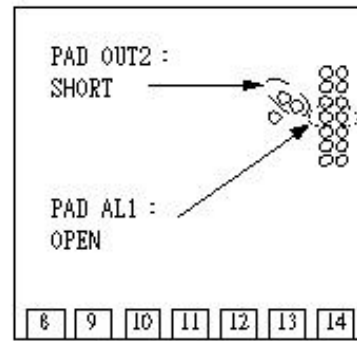
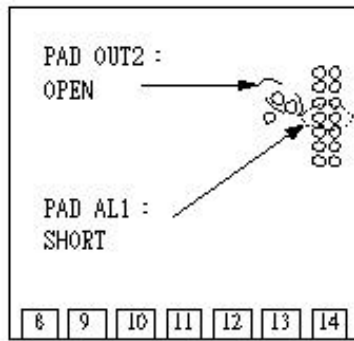
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## 7. Modification of HEAT/ALARM → HEAT/COOL (on PC board)

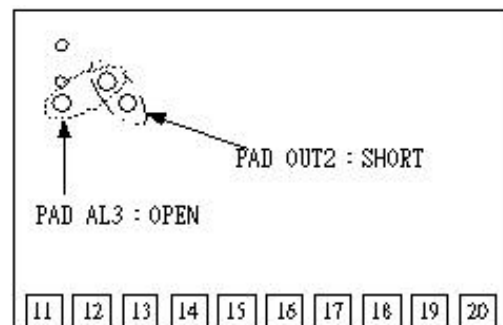
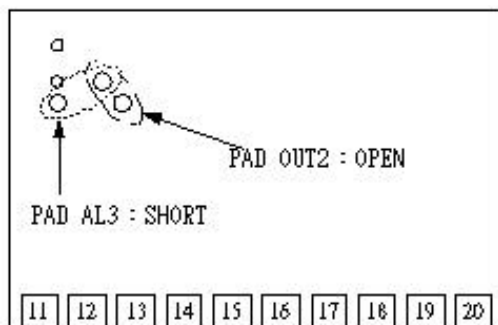
### 7.1 DC1010



### 7.2 DC1030



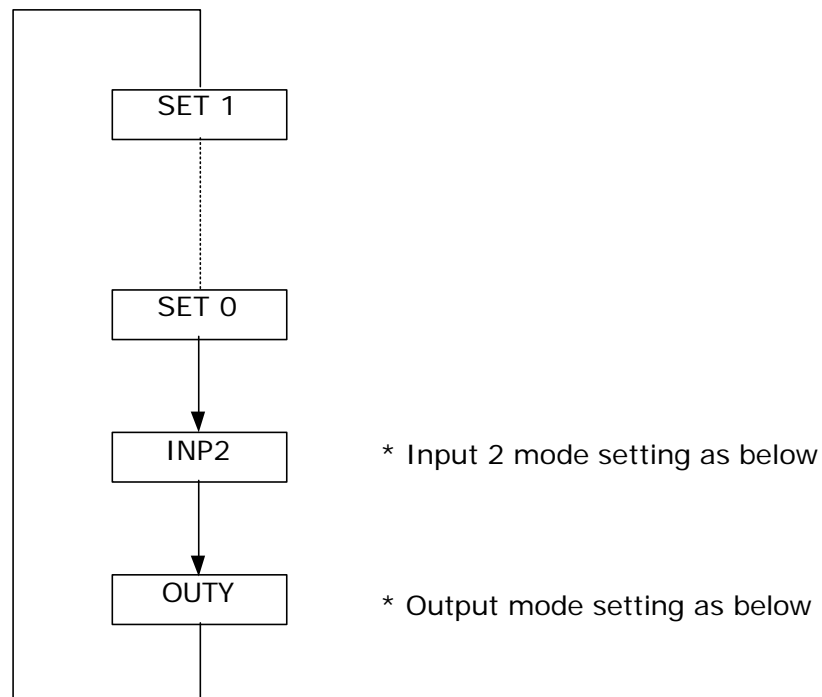
### 7.3 DC1020/1040



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## 8. Special Function Description

### 8.1 Level set



#### 8.1.1 Second input mode

INP 2 = 0, Non

INP 2 = 1, 1~5V/4~20mA/2~10V

INP 2 = 2, 0~5V/0~20mA/0~10V

#### 8.1.2 Output mode

OUTY = 0, Single output

OUTY = 1, Double output

OUTY = 2, Non

OUTY = 3, Motor Position Control

OUTY = 4, Single phase SCR (Single phase control)

OUTY = 5, Three phase SCR (Three phase control)

8.2 Ramp & Soak

8.2.1 RAMP

- i) Set "SET2.1= 1", "SET4.1= 1" at Set level
- ii) Set "ALD 3 = 9" at Input level
- iii) Then, "AL 3" menu will not be displayed

PV	<b>RAMP</b>	Range = 00.00~99.99 (°C/minute) If RAMP not used, set ALD 3 = 0
SP	<b>0000</b>	

8.2.2 SOAK

- i) ALD1/ALD2 = 19
- ii) Then, AL1/AL2 will be displayed

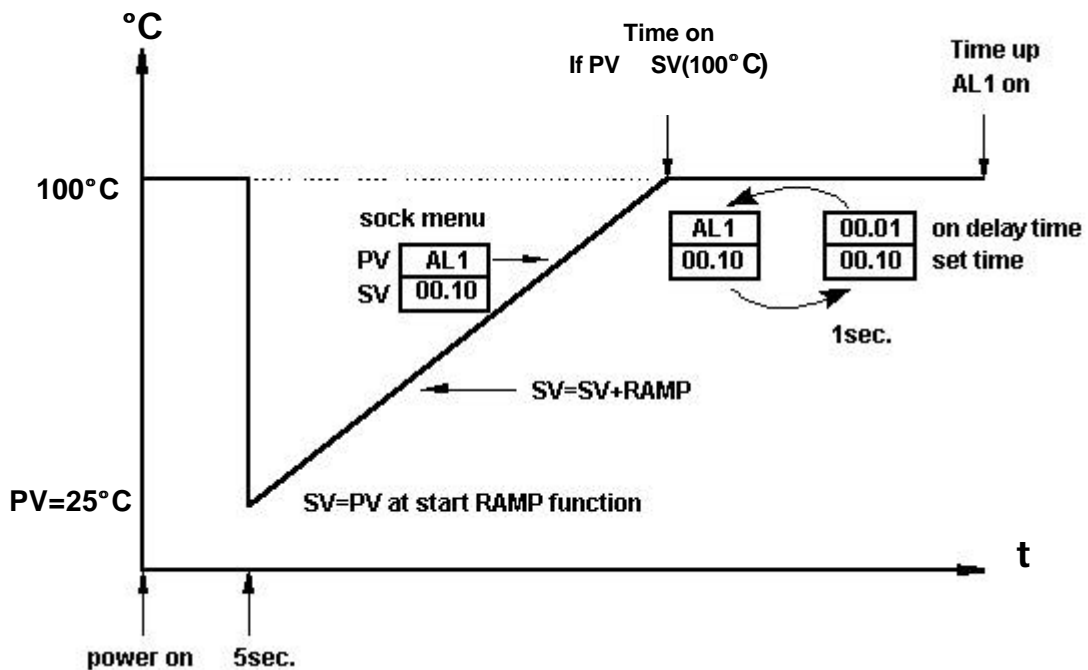
PV	<b>AL 1</b>	Range = 00.00~99.59 (hour/minute)
SP	<b>0000</b>	

Example)

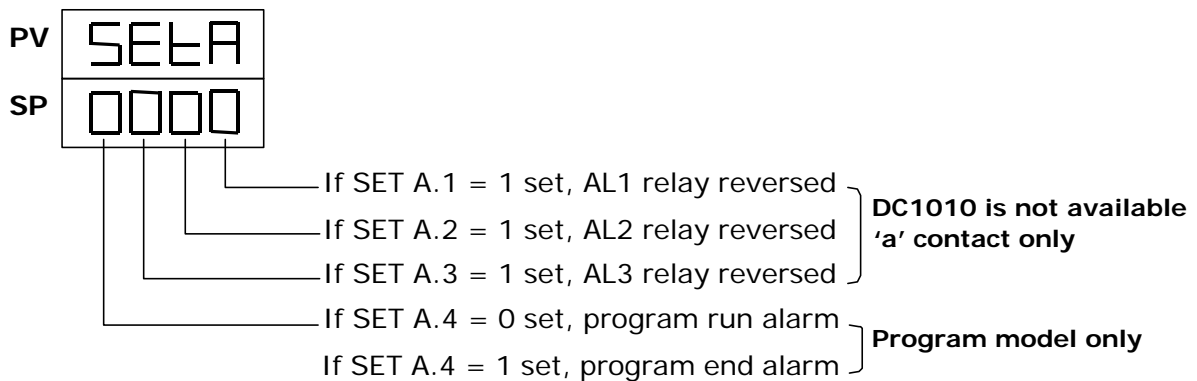
SP = 100°C, RAMP = 10.00 °C/minute

Time(minute) = 10 minute → AL1 = 00.10

PV = 25°C



- 8.3 Remote SP
  - 8.3.1 Hardware must be mounted
  - 8.3.2 Set 'INP2' to 1 or 2 (ANL2, ANH2 used for Cal.)
  - 8.3.3 SET 0.3 = 1 means Remote SP from Input 2 channel  
(\*SET 0.3 = 0 means Local SP)
- 8.4 Alarm Timer ALT1/ALT2/ALT3 description
  - 8.4.1 ALT 1 = 0 means Switching if AL 1 is ON
  - 8.4.2 ALT 1 = 99.59 means 'continuous alarm' if AL 1 is ON
  - 8.4.3 ALT 1 = 00.01~99.58 means AL 1 is on delay timer
- 8.5 Function SET A



- 8.6 Function SET 8
  - 8.6.1 SET 8.1 = 0 Non  
SET 8.1 = 1 Program Repeat
  - 8.6.2 SET 8.2 = 0 Non (program model only)  
SET 8.2 = 1 Power failure access
  - 8.6.3 SET 8.3 = 0 Zero start (program model only)  
SET 8.3 = 1 PV start
  - 8.6.4 SET 8.4 = 0 Non  
SET 8.4 = 1 Display will be transferred to single display.  
(Don't change this digit)  
\* SET 8 = 0000 can make return to double display

- 
- 8.7      Function SET 9
  - 8.7.1    SET 9.1 = 0    Non
  - SET 9.1 = 1    PV/SP switching
  - \* This is for the single display set (refer to SET 8.4)
  - 8.7.2    SET 9.2 = 0    Non
  - SET 9.2 = 1    Non Program model       : No display RAMP
  - Program model               : Timer change from H.M to M.S
  - 8.7.3    SET 9.3 = 0    Non
  - SET 9.3 = 1    Transmission SP
  - 8.7.4    SET 9.4 = 0    Non
  - SET 9.4 = 1    Transmission PV

- 8.8      Function SET 0
- 8.8.1    SET 0.1 = 0    Non
- SET 0.1 = 1    Non (function not available for DC1010/1020/1030/1040)
- 8.8.2    SET 0.2 = 0    Non
- SET 0.2 = 1    Rate for AL3 (ALD 3 = 0)
- 8.8.3    SET 0.3 = 0    Non
- SET 0.3 = 1    Remote SP
- 8.8.4    SET 0.4 = 0    Motor valve close = "b" out (contact normally close)
- SET 0.4 = 1    Motor valve close = "a" out (contact normally open)

8.9      Input level wait

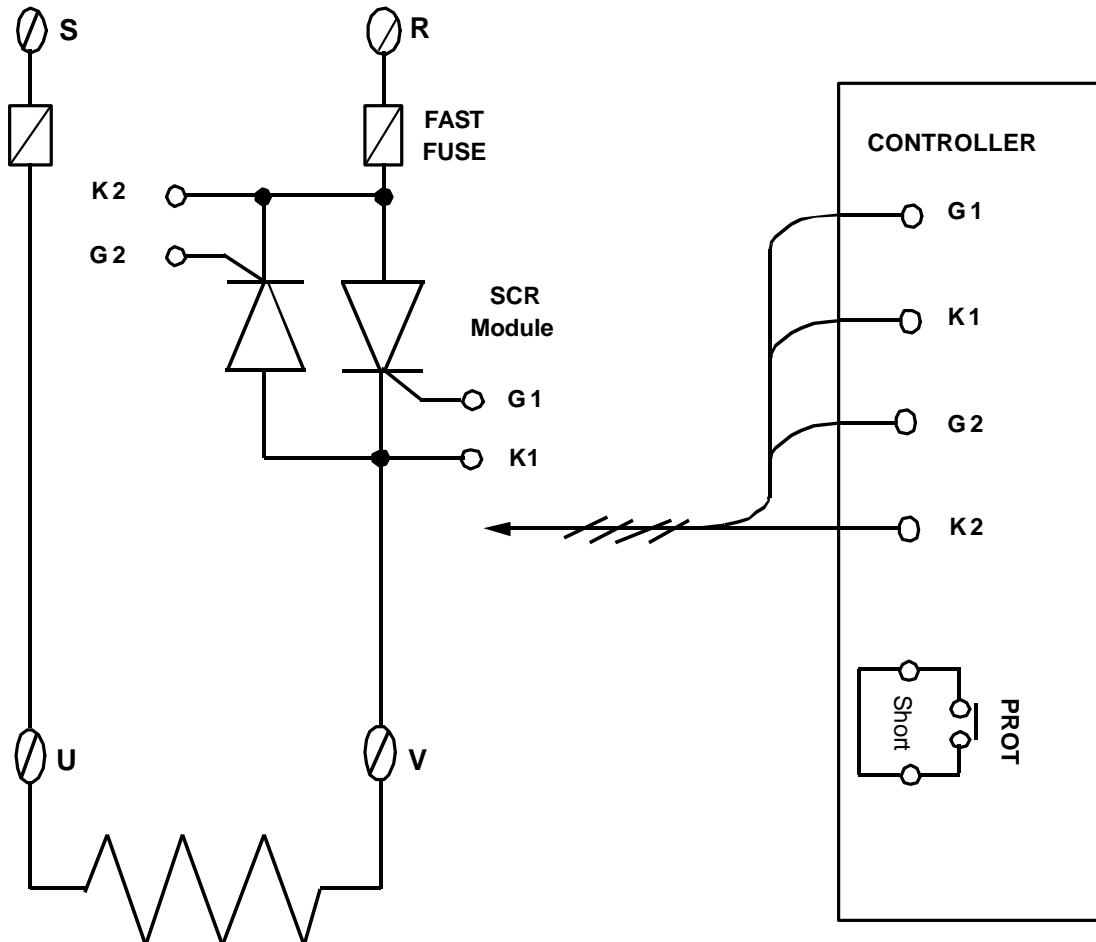
Wait = 0 means "no wait". When used as a programmer, i the

Wait ≠ 0 means "wait"

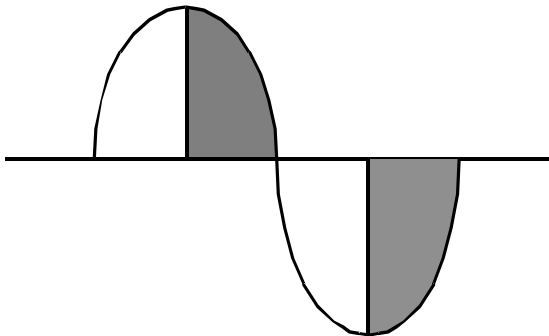
- 8.10     Cycle Time
- Range: 0~150 sec
- CYT1= 0               (i) mA
- (ii) Phase control(SCR)
- CYT1= 1               (i) SSR
- (ii) Phase zero control(SCR)
- CYT1= over 10        Relay output.

Application 1. Single Phase Control, Phase angle control

- . Available models: DC1030/1040, DC1030P/1040P
- . Data Change:
  - OUTY = 4
  - CYT = 0
  - CL01 = 0, CH01 = 5000 if used for resistance load
  - CL01 = 0, CH01 = 4000 if used for inductor load



\*\* Controller source phase must be same as load source phase





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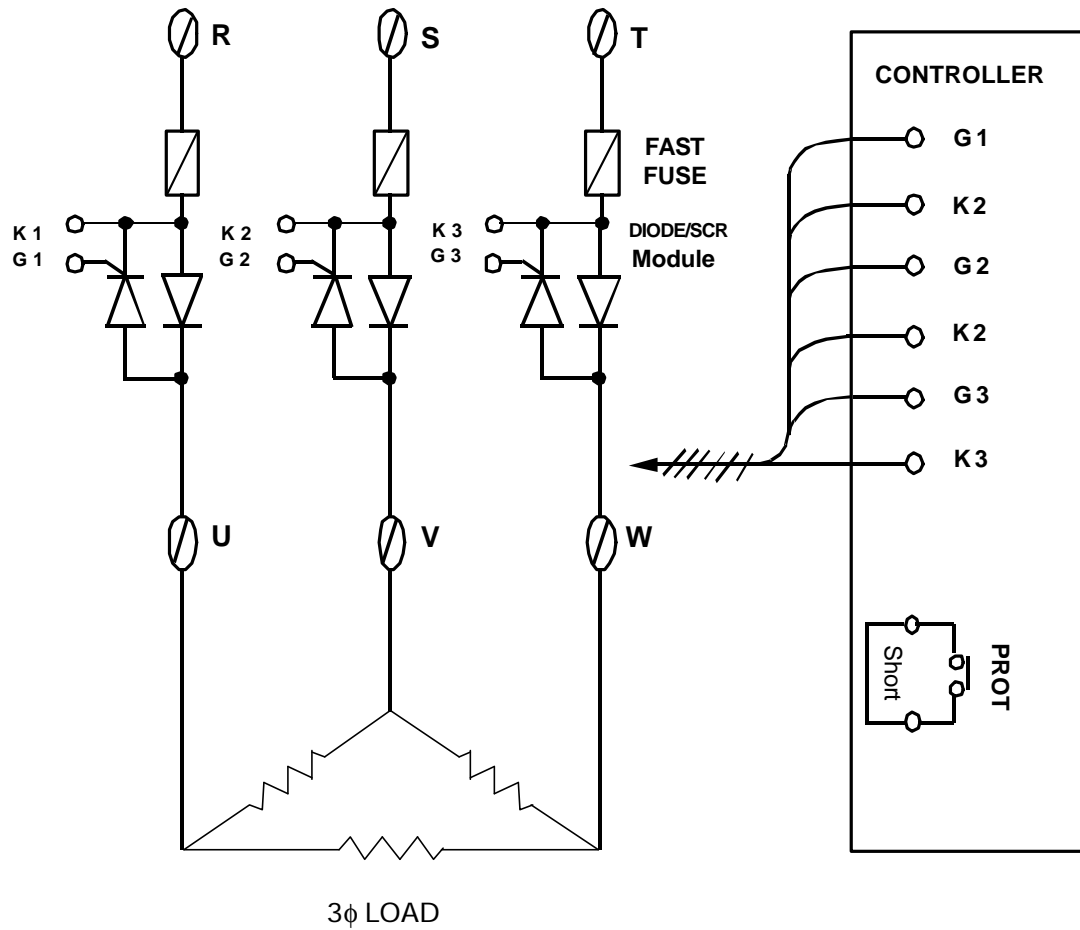
Application 2. Three Phase Control , Phase angle control

-. Available Models: DC1040/DC1040P

-. Data Change : OUTY = 5

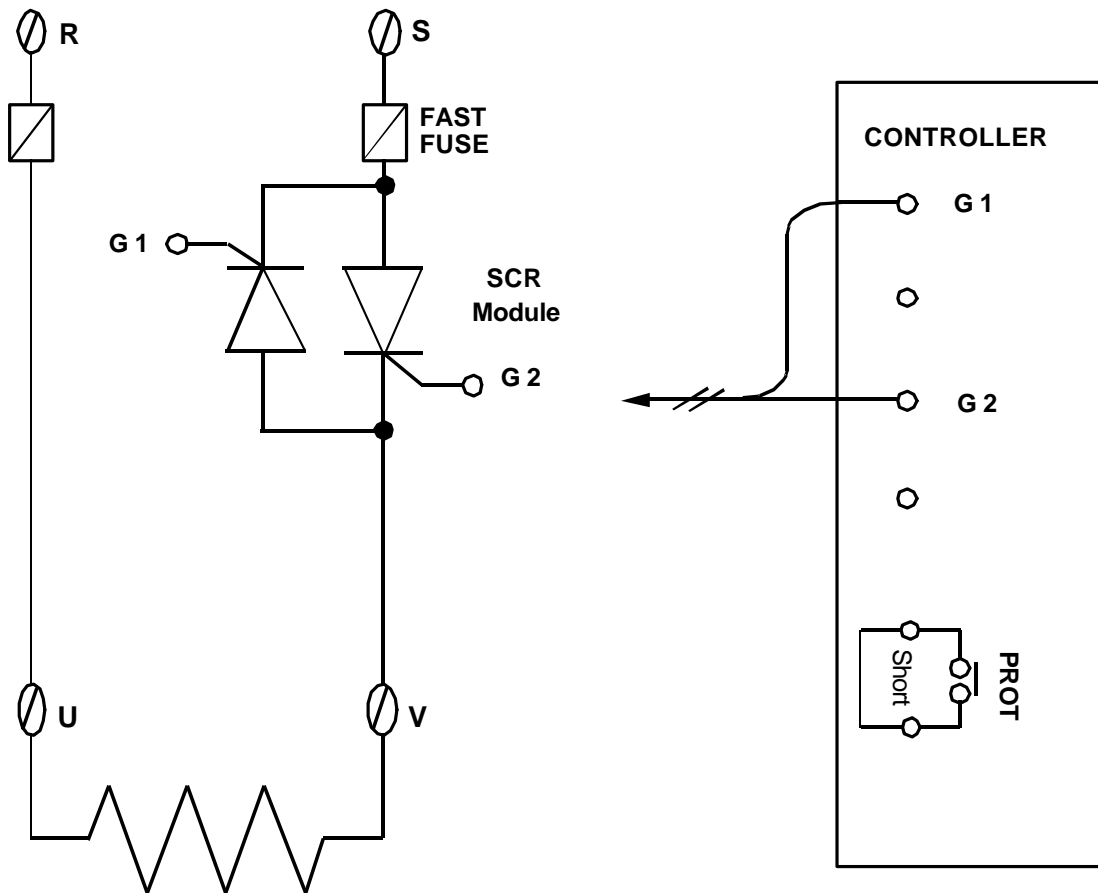
CYT = 0

CL01 = 0, CH01 = 5000 only if used for resistance load

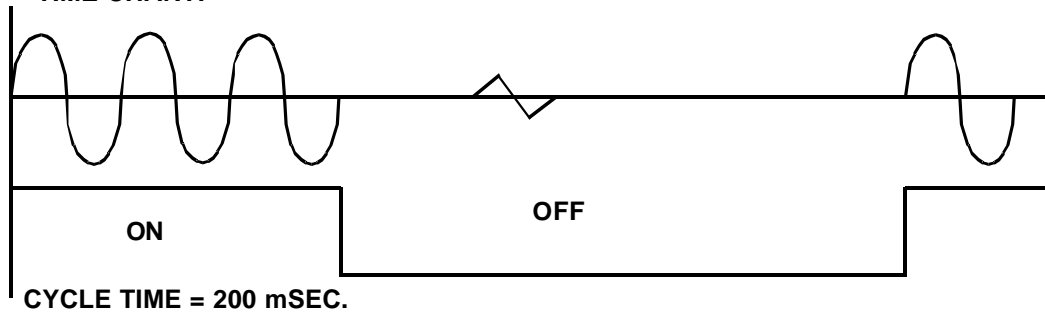


Application 3. Single Phase Zero crossover Control

- Available Models: DC1030/1040  
DC1030P/1040P
- Data Change: OUTY = 0  
CYT1 = 1

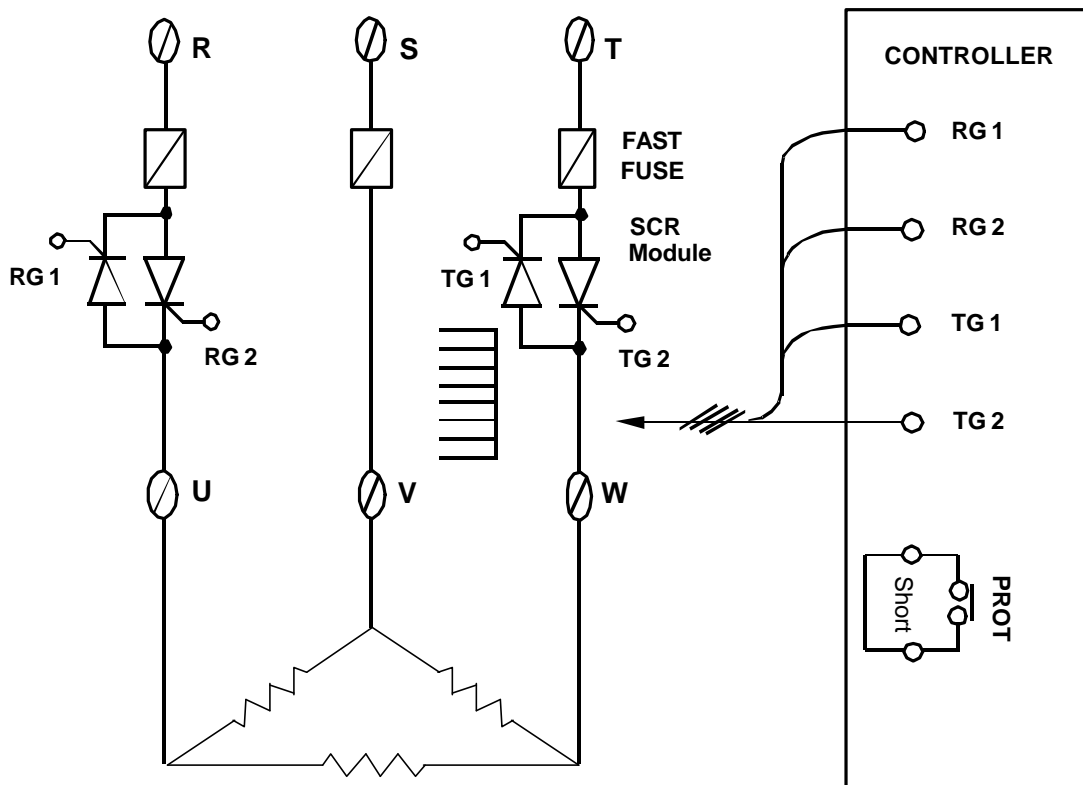


TIME CHART:

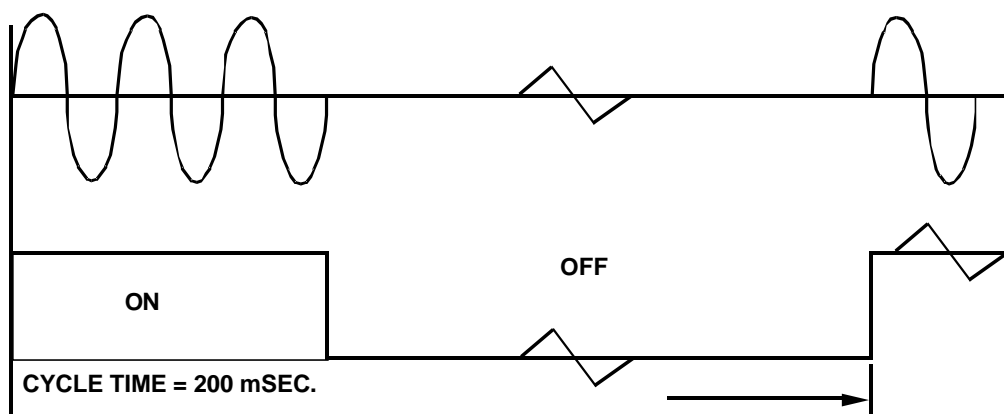


Application 4. Three Phase Zero crossover Control

- Available Models: DC1040/1040P
- Data Change: OUTY = 0  
CYT1 = 1



TIME CHART:



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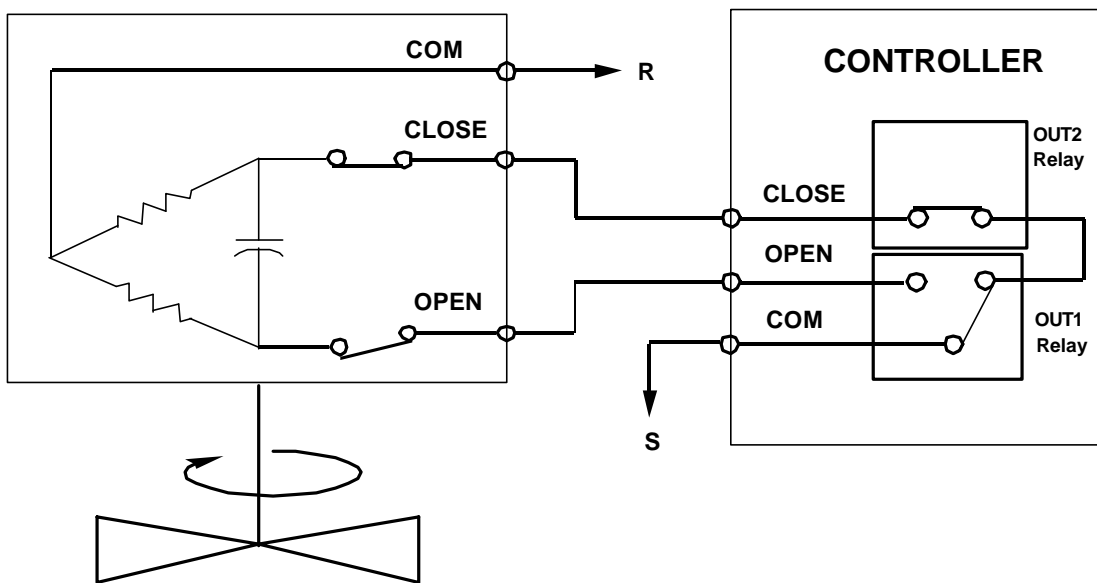
Application 5. Motor Valve Control

-. Available Models: DC1020/1030/1040  
DC1020P/1030P/1040P

-. Data Change: OUTY = 3  
CYT1 = 1~100 sec. (Normally, set 5 sec.)  
RUCY = 5~200 sec.

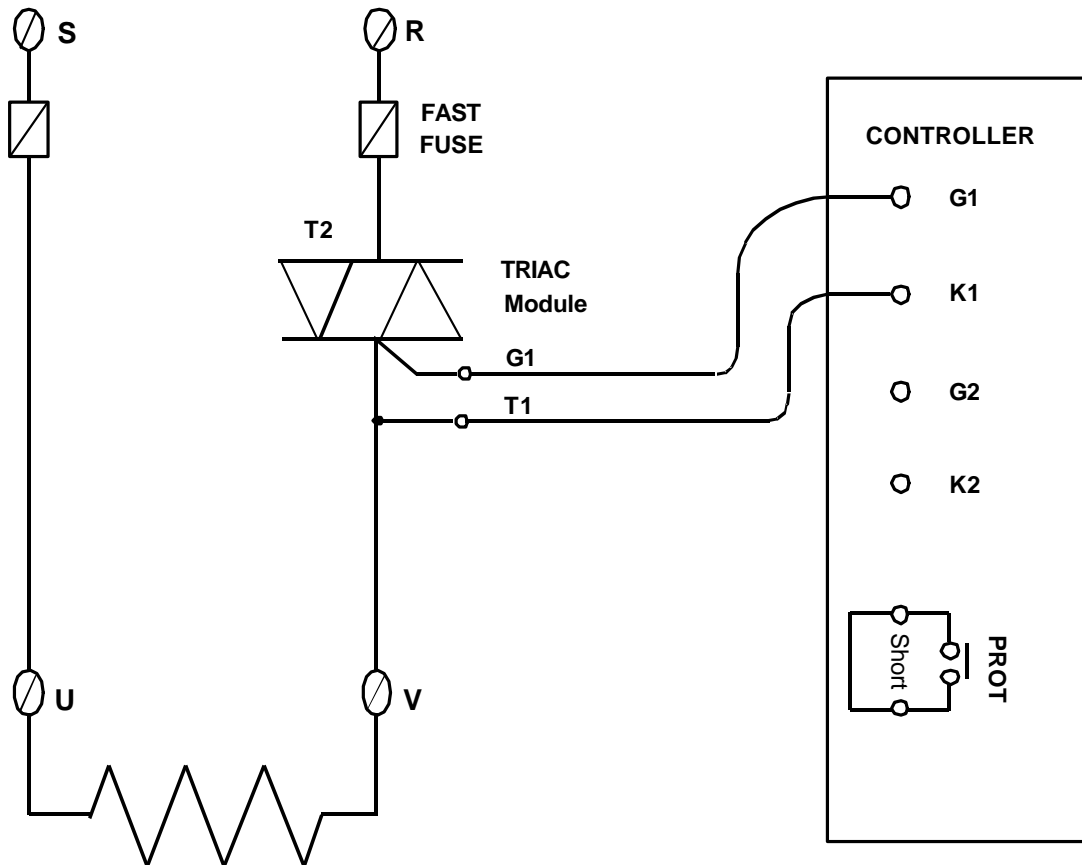
- \* 1. CYT1 is the cycle time of Open/Close
- 2. RUCY is the running time of motor valve 0~100%

**MOTOR VALVE**

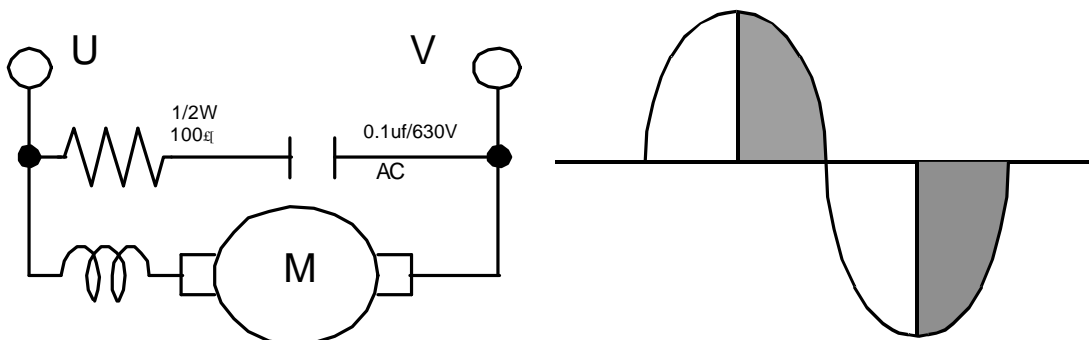


Application 6. Single Phase Control ( for TRIAC module)

- Available Models: DC1030/1040  
DC1030P/1040P
- Data Change: OUTY = 4  
CLO1=0.CHO1=5000 if use for resistance load  
CLO1=0.CHO1=4000 if use for inductor load



\*\* Controller source phase must be same as load source phase



**CONFLOW** s.p.a.

**Servizio Assistenza - Servicing Department**

**Via Lecco, 69/71**

**20041 AGRATE BRIANZA (Milano) - ITALY**

**telefono - phone : ++39 - (0)39 - 651705 / 650397**

**fax : ++39 - (0)39 - 654018**